Code: EC8T2D

IV B.Tech - II Semester – Regular/Supplementary Examinations – July 2021

GLOBAL POSITIONING SYSTEM (ELECTRONICS AND COMMUNICATION ENGINEERING)

Duration: 3 hours Max. Marks: 70

PART - A

Answer *all* the questions. All questions carry equal marks

11x 2 = 22 M

1.

- a) Explain briefly about GPS time.
- b) What do you understand about Spoofing and Anti-Spoofing?
- c) What is the function of various satellite orbits?
- d) List out GPS orbital parameters.
- e) Write a short notes on Ionospheric error.
- f) Discuss about relative velocity determination in GPS system.
- g) Give a brief description of relative positioning in the GPS system.
- h) List out standard algorithms of GPS data processing system.
- i) What are the different methods of GPS data Processing?
- j) Write the concept of flight-state monitoring of an air craft in the GPS system.
- k) Discuss about future GPS Satellites.

PART - B

Answer any *THREE* questions. All questions carry equal marks. $3 \times 16 = 48 \text{ M}$

2.	 a) Describe the basic concept of GPS system and its architecture with the help of various Segments and n diagrams. 	eat 8 M
1	b) Explain about the Signal structure of the GPS signals.	8 M
3.	a) Discuss about GPS orbital parameters and the signification of RINEX format used in GPS.	icance 10 M
1	b) Discuss about GPS Position determination.	6 M
4.	Explain the following terms in GPS system a) Clock error b) Multipath ionosphericerror c) Tropospheric error	5 M 5 M 6 M
5.	a) Discuss about the parameterization and Algorithms of Data processing.	of GPS 8 M
1	b) Compare single point positioning and relative positioning in GPS data processing.	8 M

- 6. a) Briefly explain the software development Algorithms for GPS systems. 8 M
 - b) Explain the precise kinematic positioning and the Concept of Flight-State Monitoring system. 8 M